

Prop 1:

Assume every component of ∂S contains at most 1 point from V . Then $A(S, V)$ is contractible.

Prop 2:

If V' obtained from V by adding a point $v' \in V'$ to a component of ∂S that already contain at least one point,

then $A(S, V') \cong \sum A(S, V)$
 "suspension"

$\Downarrow$
 Morer's thm.

$(X \text{ contractible} \Rightarrow \sum X \text{ contr.}, \sum S^n \cong S^{n+1})$

Proof of prop 1:

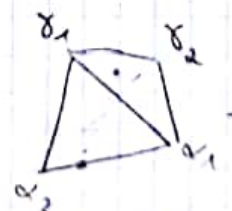
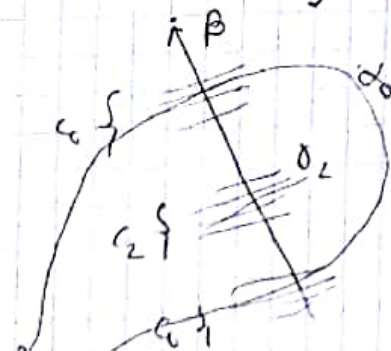
A point $p \in A(S, V)$ belongs to some simplex $p \in [\alpha_0, \dots, \alpha_k]$
 & then $p = \sum_{i=0}^k c_i \alpha_i$, $\sum c_i = 1$, $c_i \geq 0$.

We'll construct a deformation retract from $A(S, V)$ to the star of some vertex $[\beta]$

This is enough, as a star is contractible.



We choose some orientation to β . If $\alpha_0, \dots, \alpha_k$ don't intersect β we do nothing; $P_t = p \forall t \in [0, 1]$ (since p is already in the star)



At time $\frac{c_0}{\theta}$ we "get rid" of α_0 & replace it by α_1 & α_2 .

At first, we replace an ϵ of the weight of α_0 with

$$\frac{\epsilon}{2} \alpha_1 + \frac{\epsilon}{2} \alpha_2$$

The image of p at time t is denoted p_t .

Note:

(*) $p_1 \in \text{Star}([p])$ because there are no intersections left with p .

(*) the map $p \mapsto p_t$ is continuous inside every simplex
 $(\forall t \in [0, 1])$

(*) The restriction of the map $p \mapsto p_t$ to a face f of a simplex, is equal to the map on this face f .

Proof of Prop 2:

$$V' = V \cup \{v'\}$$

$A(S, V')$:

$$X = \{ E \subseteq A(S, V') \mid p, p' \in E \}$$

$$\text{Star}([p]) \cup \text{Star}([p']) \cup X = A(S, V')$$

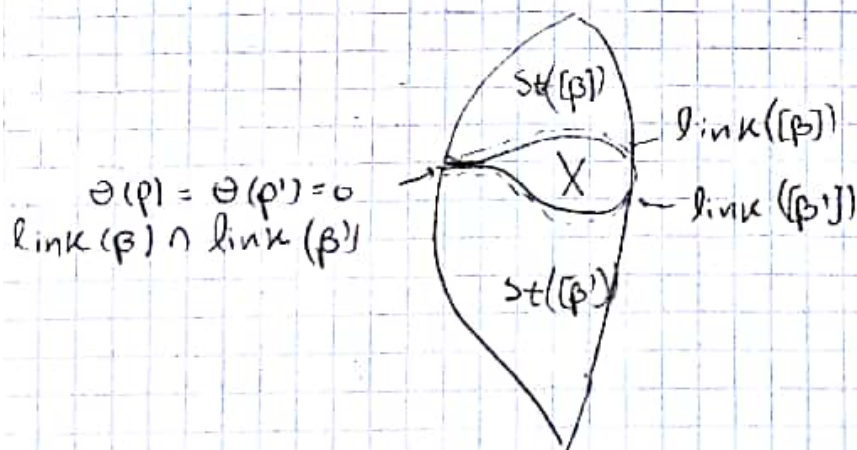
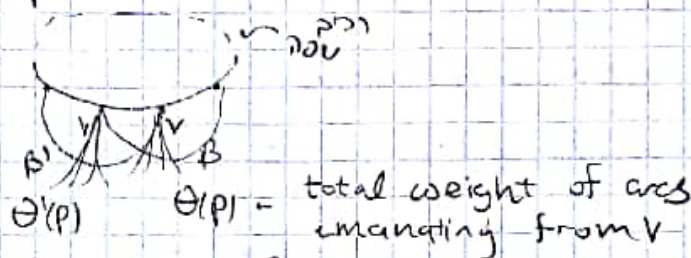
$$X \cap \text{Star}([p]) = \text{link}(p)$$

$$X \cap \text{Star}([p']) = \text{link}(p')$$

$$\text{Star}([p]) \cap \text{Star}([p']) = \text{link}([p]) \cap \text{link}([p']) \subseteq X$$

$$p \in \text{Star}([p]) \iff \theta(p) = 0$$

$$p \in \text{Star}([p']) \iff \theta'(p) = 0.$$



$$\Sigma A(S, V) = A(S, V) \times [1, 1] / \begin{matrix} (x_1, 1) \sim (x_2, 1) \\ (x_1, -1) \sim (x_2, -1) \end{matrix} \rightarrow \begin{matrix} \text{diagram of } \Sigma A(S, V) \end{matrix}$$

$f: X \rightarrow A(S, V)$ defined by collapsing the segment between v & v' to a point & deleting/merging arcs if necessary.

The following is an embedding of X into $\Sigma A(S, V)$

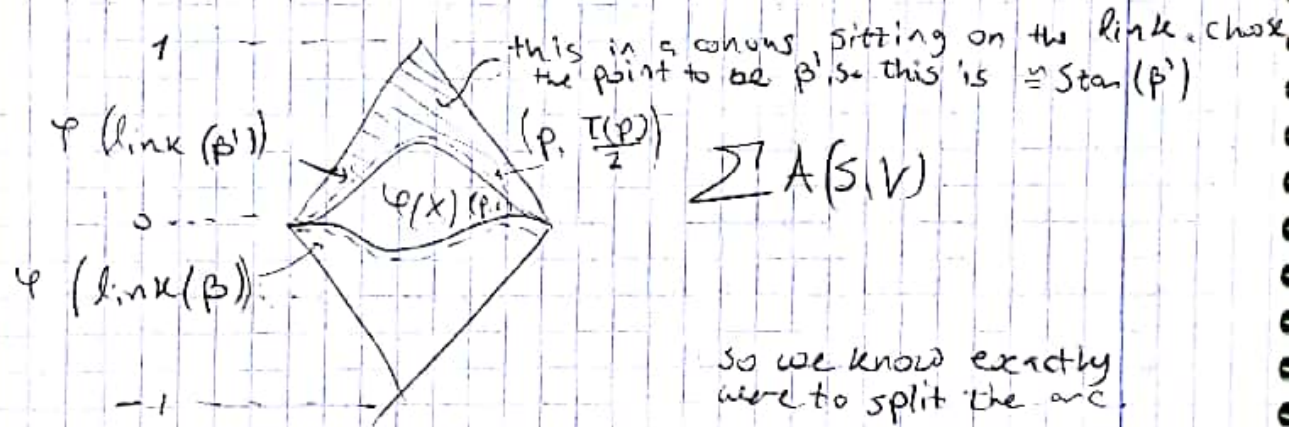
$$p \mapsto \left(\bar{p}, \frac{\theta(p) - \theta'(p)}{2} \right), \quad \begin{matrix} \theta(p) \in [0, 1] \\ \theta'(p) \in (0, 1) \end{matrix}$$

$\in [-\frac{1}{2}, \frac{1}{2}]$

(*) This function is continuous

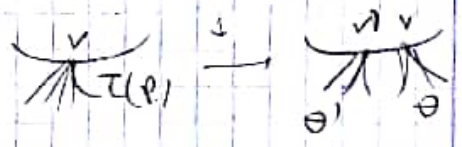
(*) f is onto (simply take a point in $A(S, V)$ & consider it as a pt in $A(S, V')$)

$$\text{Image}(\varphi) = \left\{ (p, r) \mid r \in \left[-\frac{\tau(p)}{2}, \frac{\tau(p)}{2} \right] \right\}$$



so we know exactly where to split the arc

$$\tau(p) = \theta + \theta', \quad r = \frac{\theta - \theta'}{2} \quad \text{so}$$



example:

