

Lecture 3: (from next Sunday - shreiber 007)  
only on Sundays.

11/3/2017

Thm.: connected

Classification of closed surfaces (Dehn - Heegard 1907):

Every closed surface is one of the following.

canonical form

E.C

orientability

$\pi_1$

1) Sphere  $S^2$

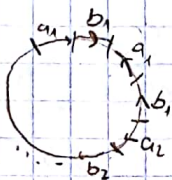
$a \circ a$

2

+

$\{e\}$

2)  $\underbrace{T \# T \# \dots \# T}_n$

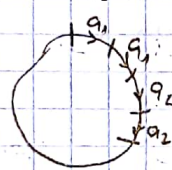


$2-2n$

+

$\langle a_1, b_1, \dots, a_n, b_n \mid [a_1, b_1], \dots, [a_n, b_n] \rangle$

3)  $\underbrace{P \# \dots \# P}_n$



$2-n$

-

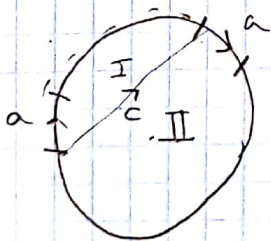
$\langle a_1, \dots, a_n \mid a_1^2 a_2^2 \dots a_n^2 \rangle$

Why every connected closed surface is homeomorphic to one of these?

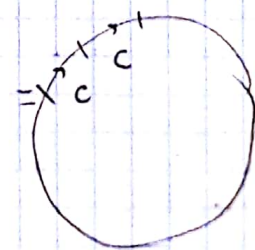
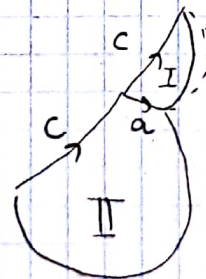
Step 1: Reduction to a single equivalence class of vertices.

Step 2: Crosscap normalization:

All pairs of like oriented edges replaced by adjacent pairs.



cut along c  
paste along a



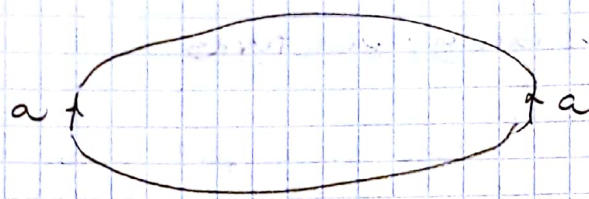
Step 3: Handle normalization.

Claim:

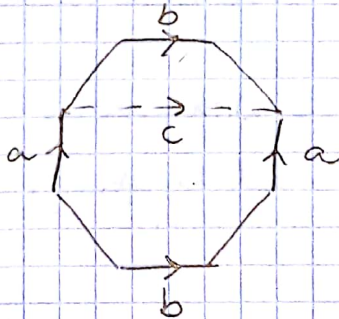
Every pair of opposite oriented edges must occur as "crossed" pairs.

$\dots a \dots b \dots a^{-1} \dots b^{-1} \dots$

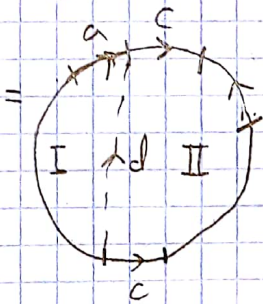
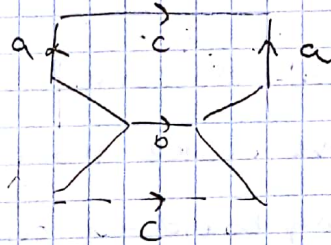
Pf.:



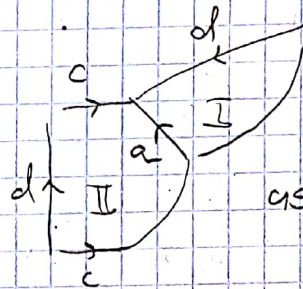
Otherwise, the upper vertices are not glued with the bottom ones.



cut along  $c$   
paste along  $b$

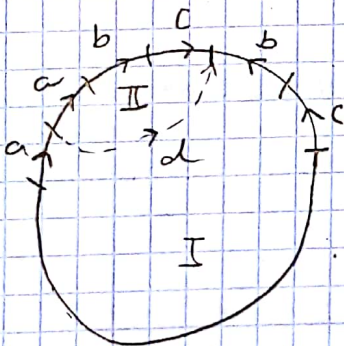


cut along  $d$   
paste along  $a$

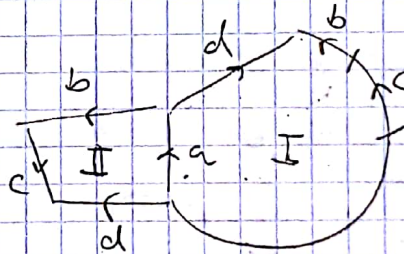


here  $c^{-1}dc d^{-1}$   
as a subword.

Step II: If both crosscaps & handles  $\Rightarrow$  only crosscaps



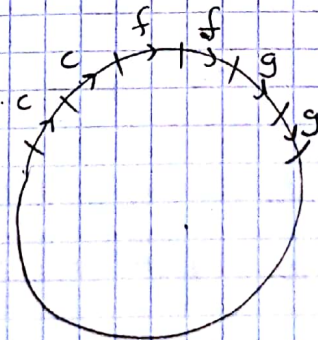
cut along  $d$   
paste along  $a$



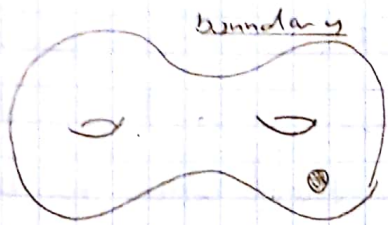
(exercise)

crosscap normalization

b then c then d



## Surfaces with boundary/punctures



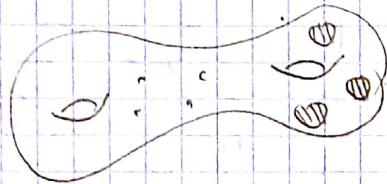
where every point looks locally, either like  $\mathbb{R}^2$  or like:

Punctures: points removed from the surface  $\Rightarrow$  no longer compact

classification of connected compact surfaces with punctures:

On top of the choice from the above list, we need to specify

- 1) how many boundary components  $\in \mathbb{N}$
- 2) how many punctures  $\in \mathbb{N}$



Note:

All compact surfaces with a boundary can be embedded into  $\mathbb{R}^3$ .

