

67D1

22/04/2012

הצגה

(הצגה) : אורך של מסלול

$$L(\gamma) = \int_a^b |\gamma'(t)| dt$$

- (הצגה) : γ מסלול סגור, $\gamma(a) = \gamma(b)$

הצגה : $\gamma \in C(G)$, $\gamma \subset G$, $\gamma(a) = \gamma(b)$

הצגה : F פונקציה אנליטית, $F'(z) = f(z)$

$$\int_{\gamma} f(z) dz = 0$$

$$\int_{\gamma} f(z) dz = \int_a^b F'(\gamma(t)) \gamma'(t) dt = F(\gamma(b)) - F(\gamma(a)) = 0$$

$$f(z) = \frac{1}{z} \left(z + \frac{1}{z} \right)^{2n}$$

$$w(t) = e^{it}$$

$$t \in [0, 2\pi]$$

$$I = \int_{\gamma} f(z) dz$$

$$f(e^{it}) = \frac{1}{e^{it}} \left(e^{it} + \frac{1}{e^{it}} \right)^{2n} = \frac{2^{2n} (\cos t)^{2n}}{e^{it}}$$

$$w'(t) = ie^{it}$$

$$I = \int_0^{2\pi} f(e^{it}) \cdot ie^{it} dt = i \cdot 2^{2n} \int_0^{2\pi} (\cos t)^{2n} dt$$

$$f(z) = \frac{1}{z} \cdot \sum_{k=0}^{2n} \binom{2n}{k} z^k = \sum_{k=0}^{2n} \binom{2n}{k} z^{k-1}$$

$$= \sum_{k=0}^{2n} \binom{2n}{k} z^{k-1}$$

$$II = \int_{\gamma} f(z) dz = \sum_{k=0}^{2n} \binom{2n}{k} \int_{\gamma} z^{k-1} dz$$

⊕

$$II = \binom{2n}{n} \cdot \int_{\gamma} \frac{1}{z} dz = \binom{2n}{n} \int_0^{2\pi} \frac{e^{it}}{e^{it}} dt = 2\pi i \cdot \binom{2n}{n}$$

$$\int_{\gamma} \frac{1}{z} dz = 2\pi i$$

⊕

$$I = II \quad (b.p.) \quad , p \parallel$$

$$\int_0^{2\pi} (\cos t)^{2n} dt = \frac{2\pi}{2^{2n}} \binom{2n}{n}$$

25/10/20

$$\varphi: [c, d] \rightarrow [a, b]$$

$$\varphi \in C^1[c, d], \quad \varphi'$$

$$\varphi(c) = a$$

$$\varphi(d) = b$$

$$\gamma: [a, b] \rightarrow \mathbb{C}$$

$$\gamma_1 = \varphi \circ \gamma: [c, d] \rightarrow \mathbb{C}$$

$$\text{Im } \gamma = \text{Im } \gamma_1$$

"now call" γ_1 γ no for γ_1

$$\angle(\gamma_1) = \angle(\gamma) \quad \text{OK}$$

$$\text{if } \gamma \in C$$

$$f \in C(\mathbb{C}) \quad \text{OK}$$

$$\int_{\gamma_1} f(z) dz = \int_{\gamma} f(z) dz$$

OK

$$\int_{\gamma_1} f(z) dz = \int_c^d f(\gamma(u(s))) \cdot (\gamma(u(s)))' ds$$

$$u(s) = t, \quad (\gamma \circ u)'(s) = \gamma'(t) u'(s)$$

$$\int_0^b f(\gamma(t)) \gamma'(t) dt = \int_0^b f(\gamma(t)) \gamma'(t) dt = \int_{\gamma} f(z) dz$$